

**GUJARAT TECHNOLOGICAL UNIVERSITY****BE - SEMESTER-VII (NEW) EXAMINATION – WINTER 2021****Subject Code:3170916****Date:15/12/2021****Subject Name:Advanced Electric Drives****Time:10:30 AM TO 01:00 PM****Total Marks: 70****Instructions:**

1. Attempt all questions.
2. Make suitable assumptions wherever necessary.
3. Figures to the right indicate full marks.
4. Simple and non-programmable scientific calculators are allowed.

		<b>MARKS</b>
<b>Q.1</b>	(a) State in brief, how torque is estimated in closed loop control of electric drives.	<b>03</b>
	(b) Explain in brief, the control of Current Source Inverter with necessary diagram.	<b>04</b>
	(c) Explain PWM converter as line side rectifier with necessary figure.	<b>07</b>
<b>Q.2</b>	(a) Describe Selected Harmonic Elimination with necessary figure.	<b>03</b>
	(b) Draw the block diagram of Electric drive and explain each block in brief.	<b>04</b>
	(c) Explain operation of H bridge as a 4-Q drive.	<b>07</b>
<b>OR</b>		
	(c) Draw and explain the equivalent circuit of a single –phase induction machine.	<b>07</b>
<b>Q.3</b>	(a) State advantages of vector control over scalar control.	<b>03</b>
	(b) Compare VSI and CSI fed drives.	<b>04</b>
	(c) Write a note on Reference-frame theory, and state commonly used reference frames.	<b>07</b>
<b>OR</b>		
<b>Q.3</b>	(a) Compare DTC and FOC	<b>03</b>
	(b) Discuss what will happen if V/f ratio is not kept constant in IM drive.	<b>04</b>
	(c) Draw and explain operation of open loop V/f control of Induction motor with PWM voltage fed converter.	<b>07</b>
<b>Q.4</b>	(a) List different permanent magnet motors.	<b>03</b>
	(b) Draw block diagram of synchronous motor drive.	<b>04</b>
	(c) Explain direct torque control of synchronous motor.	<b>07</b>
<b>OR</b>		
<b>Q.4</b>	(a) Draw block diagram for closed loop speed control of SRM.	<b>03</b>
	(b) List different control techniques of PMSM.	<b>04</b>
	(c) Explain CSI fed synchronous motor drives.	<b>07</b>
<b>Q.5</b>	(a) List various topologies of SRM drives.	<b>03</b>
	(b) Discuss PWM module in DSP.	<b>04</b>
	(c) State the eight different possible switching vectors in SVM with diagram. Describe sectors in the same.	<b>07</b>
<b>OR</b>		
<b>Q.5</b>	(a) Draw figure showing construction of any one type of BLDC motor.	<b>03</b>
	(b) Write a short note on TMSLF2407 with reference to motion control.	<b>04</b>
	(c) State names of some DSPs used in motion control and discuss the use of same.	<b>07</b>

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