

**GUJARAT TECHNOLOGICAL UNIVERSITY****BE - SEMESTER-IV (NEW) EXAMINATION – SUMMER 2024****Subject Code:2141708****Date:18-07-2024****Subject Name:Control System****Time:10:30 AM TO 01:00 PM****Total Marks:70****Instructions:**

1. Attempt all questions.
2. Make suitable assumptions wherever necessary.
3. Figures to the right indicate full marks.
4. Simple and non-programmable scientific calculators are allowed.

		MARKS
<b>Q.1</b>	(a) Compare Block diagram method and signal flow diagram method with suitable example.	<b>03</b>
	(b) Explain open loop system with suitable	<b>04</b>
	(c) Derive the expression of delay time, Peak Overshoot and Rise time for under damped second order system with unit step input.	<b>07</b>
<b>Q.2</b>	(a) State the properties of state transition method.	<b>03</b>
	(b) Draw the polar plot of $G(s) = (s + 2) / [(s + 1)^* (s - 1)]$ . Discuss stability too.	<b>04</b>
	(c) Discuss the step response of second order system for various values of damping ratio (i) $\zeta > 1$ (ii) $\zeta = 1$ (iii) $0 < \zeta < 1$ (iv) $\zeta = 0$ , with associated diagrams.	<b>07</b>
<b>OR</b>		
	(c) Discuss the main difference between transfer function approach and state space approach, with appropriate examples	<b>07</b>
<b>Q.3</b>	(a) Explain the concept of linearity and time invariance in the context of control system.	<b>03</b>
	(b) Describe the various details about types and orders of the control system, with suitable example.	<b>04</b>
	(c) Discuss the procedure to convert State model in to transfer function form, and vice versa, with the example of Armature control DC MOTOR.	<b>07</b>
<b>OR</b>		
<b>Q.3</b>	(a) Discuss the benefits of closed loop system over open loop system.	<b>03</b>
	(b) Define bandwidth, gain margin and phase margin for frequency response, with suitable example.	<b>04</b>
	(c) Derive the governing Diff. equation for The Gear Train and find its analogous network. Discuss the force-voltage and force-current analogy.	<b>07</b>
<b>Q.4</b>	(a) Define following terms of Signal Flow Graph. Node, Loop, Self Loop	<b>03</b>
	(b) Enlist the characteristics of positive feedback and Discuss in Brief.	<b>04</b>
	(c) Write the rules for drawing Root locus for open loop TF having gain K.	<b>07</b>
<b>OR</b>		
<b>Q.4</b>	(a) Discuss the effect of time delay on the stability of the process.	<b>03</b>
	(b) Determine the stability of the system $s^5 + s^4 + 2s^3 + 2s^2 + 3s + 5 = 0$ . Comments on the results.	<b>04</b>
	(c) What is M circle and N circles in Nyquist plot? Discuss its importance in Nichols chart.	<b>07</b>
<b>Q.5</b>	(a) Discuss the various standard test signals used in control system analysis, with diagram and mathematical formulae/equations.	<b>03</b>
	(b) Explain Initial value theorem and Final Theorem in Laplace Transformation, with supported proof.	<b>04</b>
	(c) Sketch the Root locus for the unity feedback system whose open loop transfer function is given by $G(s) = K / s^*[(s + 4)^*(S^2 + 4s + 20)]$ .	<b>07</b>

**OR**

- Q.5** (a) Explain following: absolute stability, relative stability and BIBO stability, with examples. **03**  
(b) Write a technical note on steady state error and error constants with appropriate example and calculations. **04**  
(c) Draw the Bode plot for a system having TF  $(s)H(s) = 64*(s + 2) / s * [(s + 0.5)*(s^2 + 3.2s + 64)]$ . Find **07**  
Gain margin, Phase margin and Cross over frequencies.

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