

GUJARAT TECHNOLOGICAL UNIVERSITY**BE – SEMESTER- VII EXAMINATION-SUMMER 2023****Subject Code: 2171903****Date: 21/06/2023****Subject Name: Computer Aided Manufacturing****Time: 10:30 AM TO 01:00 PM****Total Marks: 70****Instructions:**

1. Attempt all questions.
2. Make suitable assumptions wherever necessary.
3. Figures to the right indicate full marks.
4. Simple and non-programmable scientific calculators are allowed.

		Marks
Q.1	(a) How NC/CNC is better than conventional manufacturing? Explain.	3
	(b) With the help of suitable figure explain Axis Identification for lathe and milling machine.	4
	(c) Elaborate the role of elements of CIM with the help of CIM wheel	7
Q.2	(a) Explain the any types of code structures used in GT classification citing illustrations.	3
	(b) Describe with sketch the working and construction of recirculating ball screw used in CNC machine tools.	4
	(c) What is group technology? Explain with example Opitz classification and coding system in brief	7
OR		
	(c) Differentiate between Generative process planning and Variant process planning.	7
Q.3	(a) What do you mean by FMS layout? Explain different types of FMS layouts with neat diagram.	3
	(b) Select a job of your choice and prepare a part program including a canned cycle.	4
	(c) Explain with neat sketch AS/RS system used in FMS	7
OR		
Q.3	(a) Explain the working of any two types of punched tape readers.	3
	(b) Classify CNC machine tools on the basis of: (i) Type of feedback system (ii) Type of tool motion control	4
	(c) What is Automated Guided Vehicles? Explain different types of AGVs with their advantages and limitations	7
Q.4	(a) Define Robot. Explain in brief the factors to be considered before introduction of robot in an organization.	3
	(b) What is a PLC? Explain major components of a PLC. List various applications of PLC.	4
	(c) Classify and explain robot configurations with neat sketches.	7
OR		
Q.4	(a) Explain in brief Economic Evaluation of investment in robotic Installation	3
	(b) Explain in brief Programmable Logic controllers(PLCS). Explain in detail composite part	4
	(c) Sketch and explain cylindrical and SCARA configuration of industrial robot, showing work envelope.	7
Q.5	(a) Differentiate between MRP I and MRP II	3
	(b) What are the typical outputs from MRP system? Prepare a sample output report of MRP system.	4
	(c) Explain different types of flexibilities in FMS.	7
OR		
Q.5	(a) Explain in brief about the JIT philosophy.	3
	(b) Explain various sensors and actuators used in robots.	4
	(c) What is computer integrated production management system? Explain with neat flow chart.	7