

**GUJARAT TECHNOLOGICAL UNIVERSITY****BE - SEMESTER-VII (NEW) EXAMINATION – SUMMER 2022****Subject Code:2170909****Date:14/06/2022****Subject Name:Design of AC Machines****Time:02:30 PM TO 05:30 PM****Total Marks: 70****Instructions:**

1. Attempt all questions.
2. Make suitable assumptions wherever necessary.
3. Figures to the right indicate full marks.
4. Simple and non-programmable scientific calculators are allowed.

		<b>MARKS</b>
<b>Q.1</b>	(a) State the rules for the selection of rotor slots in 3-phase induction motor.	<b>03</b>
	(b) State the effect of air gap length on the performance of a 3-phase induction motor. Explain any one in brief.	<b>04</b>
	(c) Derive an output equation for 3- $\phi$ induction motor with usual notation.	<b>07</b>
<b>Q.2</b>	(a) Explain dispersion co-efficient applied to induction motors.	<b>03</b>
	(b) How design of 1-phase and 3-phase induction motor differ from each other	<b>04</b>
	(c) Prove that torque produce by 5TH harmonics is in backward direction & 7TH harmonics is in forward direction.	<b>07</b>
<b>OR</b>		
<b>Q.3</b>	(a) Explain the deciding factor for stator slots of a 3-phase induction motor	<b>07</b>
	(a) Why auxiliary winding needed in 1-phase induction motor.	<b>03</b>
	(b) Write output equation in 1-phase induction motor. Give identification of each notation in it.	<b>04</b>
	(c) Explain the design procedure of rotor for 1- $\phi$ induction motor with usual notation.	<b>07</b>
<b>OR</b>		
<b>Q.3</b>	(a) Important of circle dia. in design of motor.	<b>03</b>
	(b) Define and explain the term “short circuit ratio” of a synchronous generator.	<b>04</b>
	(c) Explain the design procedure of an auxiliary winding in case of resistance split phase 1- $\phi$ induction motor with usual notation.	<b>07</b>
<b>Q.4</b>	(a) State different materials used in alternator construction.	<b>03</b>
	(b) Explain purpose damper winding in alternator	<b>04</b>
	(c) Find the main dimensions, number of turns per phase & number of stator slots of 3- $\phi$ , 13750V, 50Hz, 1500 RPM, star connected alternator from given data : . $B_{av}= 0.62$ Wb/m <sup>2</sup> , $a_c=40000$ Amp-cond/m, $K_w=0.95$ , peripheral velocity= 79m/s., Rating=12MVA.	<b>07</b>
<b>OR</b>		
<b>Q.4</b>	(a) Explain different types of rotor used in 3-phase induction motor construction.	<b>03</b>
	(b) Explain different excitation system in alternator	<b>04</b>
	(c) Calculate the diameter, core length, no of conductors of the stator , size of conductor, no of stator slots of 75 MVA, 96 pole, 50 HZ, low speed star connected hydro generator having voltage per phase is 8000V. Assume $B_{av}= 0.64$ Wb/m <sup>2</sup> , $a_c=40625$ Amp-cond/m, $K_w=0.955$ , peripheral velocity= 39.5m/s	<b>07</b>

- Q.5** (a) Explain different types of rotor used in alternator construction. **03**  
(b) Explain why a turbo alternator has smaller diameter and large length but hydro alternator has larger diameter and small length? **04**  
(c) Find the main dimensions, number of stator turns per phase & number of stator slots for a 25KW, 415V, 50Hz, 2880rpm, 3- $\phi$  delta connected induction motor. Assume that: specific magnetic loading=0.48wb/m<sup>2</sup>, specific electric loading=21000ac/m, Efficiency=88%, power factor=0.87, stator winding factor=0.9451. Take ratio (L/ $\tau$ )=0.7 **07**

**OR**

- Q.5** (a) Explain the advantages of finite element method **03**  
(b) Discuss the design differences of a salient pole and non salient pole synchronous machines **04**  
(c) Explain significance of FEM in design problem **07**

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